## PHYS 101 - General Physics I Midterm Exam 2

1. Block $A$ in the figure has mass $m_{1}$, and block $B$ has mass $m_{2}$. The coefficient of kinetic friction between all surfaces is $\mu_{k}$. Blocks $A$ and $B$ are connected by a light, flexible cord passing around a fixed, massless, frictionless pulley. The gravitational acceleration is $g$.
(a) (5 Pts.) Draw a free body diagram for both blocks.
(b) (8 Pts.) Find the magnitude of the horizontal force $\overrightarrow{\mathbf{F}}$ necessary to drag block $B$ to the left at constant speed.
(c) (12 Pts.) Find the tension in the cord and the magnitude of the force $\overrightarrow{\mathbf{F}}$ if it is large enough to accelerate the bottom block with acceleration $a$. (Express your result in terms
 of $m_{1}, m_{2}, \mathrm{~g}, a$, and $\mu_{k}$.

## Solution:

(a)

(b) In this case, we have $\overrightarrow{\mathbf{a}}_{1}=0, \overrightarrow{\mathbf{a}}_{2}=0$.
$F_{T}-f_{1}=0, \quad f_{1}=\mu_{k} N_{1}=\mu_{k} m_{1} \mathrm{~g} \quad \rightarrow \quad F_{T}=\mu_{k} m_{1} \mathrm{~g}$.
$F-F_{T}-f_{1}-f_{2}=0, \quad f_{2}=\mu_{k} N_{2}=\mu_{k}\left(m_{1}+m_{2}\right) \mathrm{g} \quad \rightarrow \quad F=\mu_{k}\left(3 m_{1}+m_{2}\right) \mathrm{g}$.
(c) ) In this case $\left|\overrightarrow{\mathbf{a}}_{1}\right|=\left|\overrightarrow{\mathbf{a}}_{2}\right|=a$.
$F_{T}-f_{1}=m_{1} a, \quad f_{1}=\mu_{k} N_{1}=\mu_{k} m_{1} \mathrm{~g} \quad \rightarrow \quad F_{T}=m_{1}\left(a+\mu_{k} \mathrm{~g}\right)$.
$F-F_{T}-f_{1}-f_{2}=m_{2} a \rightarrow F=\left(m_{1}+m_{2}\right) a+\mu_{k} g\left(3 m_{1}+m_{2}\right)$.
2. A block of mass $m$ on a horizontal surface is attached to the end of a massless spring with stiffness constant $k$. The other end of the spring is fixed. The mass is given an initial displacement $x_{0}$ from equilibrium, and an initial speed $v_{0}$ as illustrated in the figure. The gravitational acceleration is g. Ignore friction.
(a) (9 Pts.) Find its maximum speed during its motion in terms of the given quantities.

(b) (9 Pts.) Find its maximum stretch from equilibrium in terms of the given quantities.

Now assume that there is friction between the block and the horizontal surface, and that the coefficient of kinetic friction is $\mu_{k}$.
(c) (7 Pts.) What is the total distance traveled by the block if it comes to rest at the equilibrium position of the spring?

## Solution:

(a) Since there is no friction, total mechanical energy is conserved throughout the motion.
$U_{i}=\frac{1}{2} m v_{0}^{2}+\frac{1}{2} k x_{0}^{2}$.
$U=\frac{1}{2} m v_{\max }^{2}, \quad U=U_{i} \quad \rightarrow \quad \frac{1}{2} m v_{\max }^{2}=\frac{1}{2} m v_{0}^{2}+\frac{1}{2} k x_{0}^{2} \quad \rightarrow \quad v_{\max }=\sqrt{v_{0}^{2}+\frac{k}{m} x_{0}^{2}}$.
$U=\frac{1}{2} k x_{\max }^{2}, \quad U=U_{i} \quad \rightarrow \quad \frac{1}{2} k x_{\max }^{2}=\frac{1}{2} m v_{0}^{2}+\frac{1}{2} k x_{0}^{2} \quad \rightarrow \quad x_{\max }=\sqrt{\frac{m}{k} v_{0}^{2}+x_{0}^{2}}$.
(c) Now there is friction, and the block comes to rest at the equilibrium position of the spring. This means $E_{f}=0$. Work energy theorem implies
$W_{f}=-\mu_{k} m \mathrm{~g} D=0-\frac{1}{2} m v_{0}^{2}-\frac{1}{2} k x_{0}^{2} \quad \rightarrow \quad D=\frac{1}{2 \mu_{k} m \mathrm{~g}}\left(m v_{0}^{2}+k x_{0}^{2}\right)$.
3. Two blocks of equal mass $m$ are tied by an inextensible string of length $L$, and are at rest on a horizontal frictionless plane. Another identical block, moving with velocity $\overrightarrow{\mathbf{v}}_{0}$ in a direction perpendicular to the string, hits the string at its midpoint. The incoming block drags the two masses, which finally collide and stick together. The string remains taut throughout the process. You can regard all three masses as point
 masses.
(a) (8 Pts.) What is the final velocity of the three blocks after the collision?
(b) (8 Pts.) What were the speeds of the two dragged masses just before they collide?
(c) ( 9 Pts.) What was the speed of the dragging mass when the strings made an angle $\pi / 4$ with their initial direction?

Solution: (a) Since the string is inextensible, and momentum is conserved during the collision process, all three masses move in the $x$ direction with the same velocity after the collision. Therefore,
$m \overrightarrow{\mathbf{v}}_{0}=3 m \overrightarrow{\mathbf{v}}_{f} \quad \rightarrow \quad \overrightarrow{\mathbf{v}}_{f}=\frac{1}{3} \overrightarrow{\mathbf{v}}_{0}$.
(b) Conservation of momentum in the $y$ direction means the $y$ component of the velocity of the dragged masses are equal in magnitude $v_{y}$ but opposite in direction. Furthermore, until the two dragged masses collide kinetic energy of the system remains constant. Therefore, just before the collision we have
$\frac{1}{2} m v_{0}^{2}=\frac{1}{2} m\left(\frac{v_{0}}{3}\right)^{2}+2\left\{\frac{1}{2} m\left[\left(\frac{v_{0}}{3}\right)^{2}+v_{y}^{2}\right]\right\} \quad \rightarrow \quad v_{y}=\frac{v_{0}}{\sqrt{3}}$.
So, speed is
$v=\sqrt{v_{x}^{2}+v_{y}^{2}}=\sqrt{\left(\frac{v_{0}}{3}\right)^{2}+\left(\frac{v_{0}}{\sqrt{3}}\right)^{2}} \rightarrow \quad v=\frac{2}{3} v_{0}$.
(c) The figure shows the situation at that instant. The velocity of the dragging mass is in the $x$ direction, denoted by $v$, and the two dragged masses have $x$ and $y$ velocity components denoted by $v_{x}$ and $v_{x}$, as shown. Since both energy and momentum is conserved, we have
$m v_{0}=m v+2 m v_{x} \rightarrow v+2 v_{x}=v_{0} \quad \rightarrow \quad v_{x}=\frac{v_{0}-v}{2}$,
$\frac{1}{2} m v_{0}^{2}=\frac{1}{2} m v^{2}+2\left[\frac{1}{2} m\left(v_{x}^{2}+v_{y}^{2}\right)\right] \quad \rightarrow \quad v^{2}+2 v_{x}^{2}+2 v_{y}^{2}=v_{0}^{2}$.
Since the string is inextensible, velocity of the dragged masses relative to the dragging mass must be perpendicular to the string. This means $x$ and $y$ components of the relative veocity must be equal (because of the $\pi / 4$ angle).
$v_{x-\text { rel }}=v_{x}-v, \quad v_{y-\text { rel }}=-v_{y} \quad \rightarrow \quad v_{x}+v_{y}-v=0 \quad \rightarrow \quad v_{y}=\frac{3 v-v_{0}}{2}$.
$v^{2}+2\left(\frac{v_{0}-v}{2}\right)^{2}+2\left(\frac{3 v-v_{0}}{2}\right)^{2}=v_{0}^{2} \quad \rightarrow \quad v=\frac{2}{3} v_{0}$.

So speed of the dragging mass is $v=2 v_{0} / 3$.
4. Two masses, $m$ and $2 m$ are connected by a rope that hangs over a pulley as shown in the figure. The pulley has radius $R_{0}$, moment of inertia $I$, and is mounted on frictionless bearings. Initially $m$ is on the ground and $2 m$ is at rest a distance $h$ above the ground. The gravitational acceleration is $g$. Assume that the rope does not slip on the pulley when the system is released.
(a) (7 Pts.) Use conservation of energy to determine the speed of $2 m$ just before it strikes the ground.
(b) (8 Pts.) What is the angular acceleration of the pulley during the motion?
(c) ( 10 Pts.) Now assume that there is a constant frictional torque on the pulley. If the $2 m$ is given a downward initial speed $v_{0}$ and stops just before hitting the ground after
 moving down a distance $h$, what is the magintude of the frictional torque?

## Solution:

(a)
$E_{i}=2 m \mathrm{gh}, \quad E_{f}=m \mathrm{gh}+\frac{1}{2} m v^{2}+\frac{1}{2}(2 m) v^{2}+\frac{1}{2} I\left(\frac{v}{R_{0}}\right)^{2}, \quad E_{f}=E_{i} \quad \rightarrow \quad v=\sqrt{\frac{2 m g h}{3 m+I / R_{0}^{2}}}$.
(b) From free body diagrams, we have
$T_{1}-m g=m \alpha R_{0}$,
$\left(T_{2}-T_{1}\right) R_{0}=I \alpha$,
$2 m \mathrm{~g}-T_{2}=2 m \alpha R_{0}$,


where we have used $a=\alpha R_{0}$. (The rope does not slip on the pulley.) Solving these equations for $\alpha$, we get
$\alpha=\frac{m g R_{0}}{3 m R_{0}^{2}+I}=\frac{1}{R_{0}}\left(\frac{m \mathrm{~g}}{3 m+I / R_{0}^{2}}\right)$.
Or:
$a t_{f}=v, \quad \frac{1}{2} a t_{f}^{2}=h \quad \rightarrow \quad a=\frac{v^{2}}{2 a}, \quad \alpha=\frac{a}{R_{0}}=\frac{v^{2}}{2 R_{0} h}=\frac{1}{R_{0}}\left(\frac{m \mathrm{~g}}{3 m+I / R_{0}^{2}}\right)$.
(c) Let $\tau$ denote the frictional torque. As the masses move the distance $h$ the pulley rotates through the angle $h / R_{0}$. Work done by friction is equal to the change in the total mechanical energy of the system. We have
$E_{i}=\frac{1}{2} m v_{0}^{2}+\frac{1}{2}(2 m) v_{0}^{2}+\frac{1}{2} I \omega^{2}+2 m g h, \quad E_{f}=m g h, \quad W_{f}=-\tau\left(\frac{h}{R_{0}}\right)=E_{f}-E_{i}$.
So
$\tau\left(\frac{h}{R_{0}}\right)=\frac{1}{2}(3 m) v_{0}^{2}+\frac{1}{2} I\left(\frac{v_{0}}{R_{0}}\right)^{2}+m g h \quad \rightarrow \quad \tau=\frac{R_{0}}{h}\left[\frac{1}{2}\left(3 m+\frac{I}{R_{0}^{2}}\right) v_{0}^{2}+m g h\right]$.

